

M.O., 2009**Order number 2009-17 of the Minister of
Transport and of the Minister of Public Security
dated 23 November 2009**

Highway Safety Code
(R.S.Q., c. C-24.2)

REPLACEMENT of Order M.O. 2009-07 of the Minister of Transport and of the Minister of Public Security dated 9 April 2009 concerning the approval of photo radar devices and red light camera systems

THE MINISTER OF TRANSPORT,
THE MINISTER OF PUBLIC SECURITY,

CONSIDERING the first paragraph of section 332 of the Highway Safety Code (R.S.Q., c. C-24.2) which provides that the speed of a road vehicle may be measured by means of a photo radar device approved by the Minister of Transport and the Minister of Public Security and used in the manner they determine;

CONSIDERING the first paragraph of section 359.3 of the Highway Safety Code which provides that stopping at red lights may be verified by means of a camera system designed for that purpose, approved and used in the manner determined by the Minister of Transport and the Minister of Public Security;

CONSIDERING the approval of photo radar devices and red light camera systems by Order M.O. 2009-07 of the Minister of Transport and of the Minister of Public Security dated 9 April 2009;

CONSIDERING the publication of that Minister's Order in the *Gazette officielle du Québec* of 29 April 2009;

CONSIDERING the need to update the designations provided for in that Minister's Order;

ORDER AS FOLLOWS:

The Minister of Transport and the Minister of Public Security approve

1. the following mobile photo radar devices:

Manufacturer	Make	Model	Identification number
ROBOT Visual Systems GmbH and Allied Vision Technologies GmbH	Robot and Pike	MultaRadar CD with SmartCamera III and Pike F-145 cameras	ET002001
ROBOT Visual Systems GmbH and Allied Vision Technologies GmbH	Robot and Pike	MultaRadar CD with SmartCamera III and Pike F-145 cameras	ET002002
ROBOT Visual Systems GmbH and Allied Vision Technologies GmbH	Robot and Pike	MultaRadar CD with SmartCamera III and Pike F-145 cameras	ET002003

2. the following fixed photo radar devices:

Manufacturer	Make	Model	Identification number
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001001
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001002
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001003
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001004
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001005
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001006

3. the following red light camera systems:

Manufacturer	Make	Model	Identification number
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001007
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001008
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001009
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001010
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001011
ROBOT Visual Systems GmbH	Robot	TraffiStar SR 520 with detection by 2 sets of road embedded induction loops and SmartCamera III, connected to a TraffiStar-Slave with SmartCamera III	ET001012

This Minister's Order replaces Order M.O. 2009-07 of the Minister of Transport and of the Minister of Public Security dated 9 April 2009 concerning the approval of photo radar devices and red light camera systems.

This Order comes into force on the date of its publication in the *Gazette officielle du Québec*.

Québec, 23 November 2009

JULIE BOULET,
Minister of Public Security

Montréal, 30 October 2009

JACQUES P. DUPUIS,
Minister of Transport